

	Absolute Singleturn			Incremental		
	ECN 125	ECN 113	ECN 113	ERN 120	ERN 130	ERN 180
Absolute position values*	EnDat 2.2	EnDat 2.2	SSI	–		
Ordering designation	EnDat 22	EnDat 01	39n1	–		
Positions per revolution	33554432 (25 bits)	8192 (13 bits)		–		
Code	Pure binary		Gray	–		
Elec. permissible speed Deviations ¹⁾	n_{\max} for continuous position value	$\leq 600 \text{ min}^{-1}/n_{\max}$ $\pm 1 \text{ LSB}/\pm 50 \text{ LSB}$		–		
Calculation time t_{cal}	$\leq 5 \mu\text{s}$	$\leq 0.25 \mu\text{s}$	$\leq 0.5 \mu\text{s}$	–		
Incremental signals	None	$\sim 1 V_{\text{PP}}^{2)}$		\square TTL	\square HTL	$\sim 1 V_{\text{PP}}^{2)}$
Line counts*	–	2048		1000 1024	2048 2500 3600	5000
Cutoff frequency –3 dB	–	Typically $\geq 200 \text{ kHz}$		–	Typ. $\geq 180 \text{ kHz}$	
Scanning frequency	–	–		$\leq 300 \text{ kHz}$	–	
Edge separation a	–	–		$\geq 0.39 \mu\text{s}$	–	
System accuracy	$\pm 20''$			1/20 of grating period		
Power supply	3.6 to 5.25 V	$5 \text{ V} \pm 5\%$	$5 \text{ V} \pm 5\%$ ³⁾	$5 \text{ V} \pm 10\%$	10 to 30 V	$5 \text{ V} \pm 10\%$
Current consumption without load	$\leq 200 \text{ mA}$	$\leq 180 \text{ mA}$	$\leq 180 \text{ mA}$	$\leq 120 \text{ mA}$	$\leq 150 \text{ mA}$	$\leq 120 \text{ mA}$
Electrical connection*	<ul style="list-style-type: none"> • Flange socket M12, radial • Cable 1 m/5m, with M12 coupling 	<ul style="list-style-type: none"> • Flange socket M23, radial • Cable 1 m/5 m, with or without coupling M23 		<ul style="list-style-type: none"> • Flange socket M23, radial • Cable 1 m/5 m, with or without coupling M23 		
Shaft*	Hollow through shaft D = 20 mm, 25 mm , 38 mm, 50 mm			Hollow through shaft D = 20 mm, 25 mm , 38 mm, 50 mm		
Mech. permissible speed $n^4)$	$D > 30 \text{ mm}: \leq 4000 \text{ min}^{-1}$ $D \leq 30 \text{ mm}: \leq 6000 \text{ min}^{-1}$			$D > 30 \text{ mm}: \leq 4000 \text{ min}^{-1}$ $D \leq 30 \text{ mm}: \leq 6000 \text{ min}^{-1}$		
Starting torque at 20 °C	$D > 30 \text{ mm}: \leq 0.2 \text{ Nm}$ $D \leq 30 \text{ mm}: \leq 0.15 \text{ Nm}$			$D > 30 \text{ mm}: \leq 0.2 \text{ Nm}$ $D \leq 30 \text{ mm}: \leq 0.15 \text{ Nm}$		
Moment of inertia of rotor	$D = 50 \text{ mm}$	$220 \cdot 10^{-6} \text{ kgm}^2$		$D = 50 \text{ mm}$	$220 \cdot 10^{-6} \text{ kgm}^2$	
	$D = 38 \text{ mm}$	$350 \cdot 10^{-6} \text{ kgm}^2$		$D = 38 \text{ mm}$	$350 \cdot 10^{-6} \text{ kgm}^2$	
	$D = 25 \text{ mm}$	$96 \cdot 10^{-6} \text{ kgm}^2$		$D = 25 \text{ mm}$	$95 \cdot 10^{-6} \text{ kgm}^2$	
	$D = 20 \text{ mm}$	$100 \cdot 10^{-6} \text{ kgm}^2$		$D = 20 \text{ mm}$	$100 \cdot 10^{-6} \text{ kgm}^2$	
Permissible axial motion of measured shaft	$\pm 1.5 \text{ mm}$			$\pm 1.5 \text{ mm}$		
Vibration 55 to 2000 Hz Shock 6 ms	$\leq 200 \text{ m/s}^2$ ⁵⁾ (EN 60068-2-6) $\leq 1000 \text{ m/s}^2$ (EN 60068-2-27)			$\leq 200 \text{ m/s}^2$ ⁵⁾ (EN 60068-2-6) $\leq 1000 \text{ m/s}^2$ (EN 60068-2-27)		
Max. operating temp. ⁴⁾	100 °C			100 °C	85 °C (100 °C at $U_P < 15 \text{ V}$)	100 °C
Min. operating temp.	Flange socket or fixed cable: –40 °C For frequent flexing: –10 °C			Flange socket or fixed cable: –40 °C For frequent flexing: –10 °C		
Protection ⁴⁾ EN 60529	IP 64			IP 64		
Weight	0.6 kg to 0.9 kg depending on the hollow shaft version			0.6 kg to 0.9 kg depending on the hollow shaft version		

Bold: These preferred versions are available on short notice

* Please select when ordering

¹⁾ Velocity-dependent deviations between the absolute value and incremental signal

²⁾ Restricted tolerances: Signal amplitude 0.8 to 1.2 V_{PP}

³⁾ 10 to 30 V via connecting cable with voltage converter

⁴⁾ For the correlation between the protection class, shaft speed and operating temperature, see *General Mechanical Information*

⁵⁾ 100 m/s^2 with flange socket version