

	Incremental													
	ROD 420				ROD 430				ROD 480					
Incremental signals	□ TTL				□ HTL				$\sim 1 \text{ V}_{\text{PP}}^1)$					
Line counts*	50 100 150 200 250 360 500 512 720								–					
	1000 1024 1250 1500 1800 2000 2048 2500 3600 4096 5000													
Cutoff frequency –3 dB Scanning frequency Edge separation a	– $\leq 300 \text{ kHz}$ $\geq 0.39 \mu\text{s}$								$\geq 180 \text{ kHz}$ – –					
System accuracy	1/20 of grating period													
Power supply Current consumption without load	5 V $\pm 10\%$ 120 mA				10 to 30 V 150 mA				5 V $\pm 10\%$ 120 mA					
Electrical connection*	<ul style="list-style-type: none"> • Flange socket M23, radial and axial • Cable 1 m/5 m, with or without coupling M23 													
Shaft	Solid shaft D = 10 mm													
Mech. permissible speed n	$\leq 12000 \text{ min}^{-1}$													
Starting torque	$\leq 0.01 \text{ Nm}$ (at 20 °C)													
Moment of inertia of rotor	$\leq 2.3 \cdot 10^{-6} \text{ kgm}^2$													
Shaft load ²⁾	Axial 10 N/radial 20 N at shaft end													
Vibration 55 to 2000 Hz Shock 6 ms/2 ms	$\leq 300 \text{ m/s}^2$ (EN 60068-2-6) $\leq 1000 \text{ m/s}^2/\leq 2000 \text{ m/s}^2$ (EN 60068-2-27)													
Max. operating temp. ³⁾	100 °C ⁴⁾													
Min. operating temp.	Flange socket or fixed cable: –40 °C For frequent flexing: –10 °C													
Protection EN 60529	IP 67 at housing; IP 64 at shaft end ⁵⁾													
Weight	Approx. 0.3 kg													

Bold: These preferred versions are available on short notice

* Please select when ordering

1) Restricted tolerances: Signal amplitude 0.8 to 1.2 V_{PP}

2) Also see *Mechanical Design and Installation*

3) For the correlation between the operating temperature and the shaft speed or supply voltage, see *General Mechanical Information*

4) 80 °C for ROD 480 with 4096 or 5000 lines

5) IP 66 upon request